SERVICE MANUAL FOR: RUN 4.1-IWM-MP/AP Ogawa - ACTIVO_TREKPRO_T8-1



Fold Up: Manual fold up with soft drop.

Swing Arm Suspension: Yes Music Kit: Yes, MP3 input

Bluetooth: Bluetooth 3.0+Bluetooth 4.0 BLE for AP type model

Motion Control: Yes

Hand Pulse Sensor: Yes

Wireless Pulse Sensor: Polar 5.5KHz Receiver and chest belt transmitter not include/optional

Power Requirement: 230vac ± 5% 50/60Hz 5Amps

Emergency Stop: Pull down the emergency stop key (lanyard)

Speed Range: 1~18 km/h in 0.1km/h increments

Incline Range: 12 levels

Console: LCD display with blue back light

18kph/11mph Model: LCD48 IWM MP/AP for RUN4.1

Drive Motor: DC motor 4800rpm DC180V Model: GMD105-04-1B

Drive Motor Control Board: AC220v 8A Fuse:T10A/220v Model: GMC-TD30A-220V

Incline Relay Board: PWM-SD-TR100-V9

Transformer: Primacy: AC220v Second: AC12v/2000mA 17v/250mA

Model: AYY57-1220017025E

Elevation Motor: A220v model: EL-EMO-JS09-31-230

Parts List

| Part No. | Part name | Quantity |
|----------|----------------------------------|----------|
| 101 | Console housing-upper | 1 |
| 102 | Console housing-lower | 1 |
| 103 | Safety Key fix plate | 1 |
| 104 | Safety Key base | 1 |
| 105 | Safety Key | 1 |
| 106 | Loud speaker | 2 |
| 107 | Computer fixed frame | 1 |
| 109 | Pad soft cushion | 1 |
| 110 | iPad protection frame | 1 |
| 112 | Box holder-upper-Left | 1 |
| 113 | Box holder-upper-Right | 1 |
| 114 | Box holder-lower-Left | 1 |
| 115 | Box holder-lower-Right | 1 |
| 116 | Front handlebar assembly sets | 1 |
| 117 | Console tube assembly sets-Left | 1 |
| 118 | Console tube assembly sets-Right | 1 |
| 119 | Handle pluse cover sets | 2 |
| 201 | Upright tube | 2 |
| 202 | Handle bar cover-Left | 2 |
| 203 | Handle bar cover-Right | 2 |
| 204 | Upright tube lower cover | 2 |
| 205 | Handle Bar | 2 |
| 207 | Motion control sensor | 2 |
| 208 | Handlebar cover insert | 2 |
| 301 | Base Frame | 1 |

| Part No. | Part name | Quantity |
|----------|---|----------|
| 302 | Elevation support Frame | 1 |
| 303 | Elevation support Frame cover-Upper | 2 |
| 304 | Elevation support Frame cover-Lower | 2 |
| 305 | 089 Spring 2.0X ∮ 14X4 | 1 |
| 306 | Base Frame Rubber adjustment Cushion–Rear 36X10-M8X25 | 2 |
| 307 | Elevation support Frame ring cover-Left | 1 |
| 308 | Transport wheel Bracket | 1 |
| 309 | Elevation support Frame ring cover-Right | 1 |
| 310 | Transport wheel | 3 |
| 311 | Foot lock plastic cover | 1 |
| 312 | Base frame transport wheel cover –Front | 2 |
| 314 | Base Frame Rubber Cushion | 4 |
| 315 | Soft drop shock holder foot locker | 1 |
| 316 | Spring § 2.0X 6 X16.5 | 1 |
| 318 | Soft drop shock holder Nylon cover 22.5X28.2X22 | 1 |
| 319 | Gas Shock | 1 |
| 320 | Soft drop Shock tube | 1 |
| 321 | Foot locker | 1 |
| 322 | Fold up support bushing ID10X22X26X15 | 2 |
| 324 | Fold up support insert ID10XOD24X24.5 | 1 |
| 326 | Fold up support | 1 |
| 378 | Dry bearing 14X15X1.0 | 4 |
| 401 | Motor hood cover | 1 |
| 402 | Motor cover –Bottom | 1 |
| 403 | Motor Front Cover | 1 |

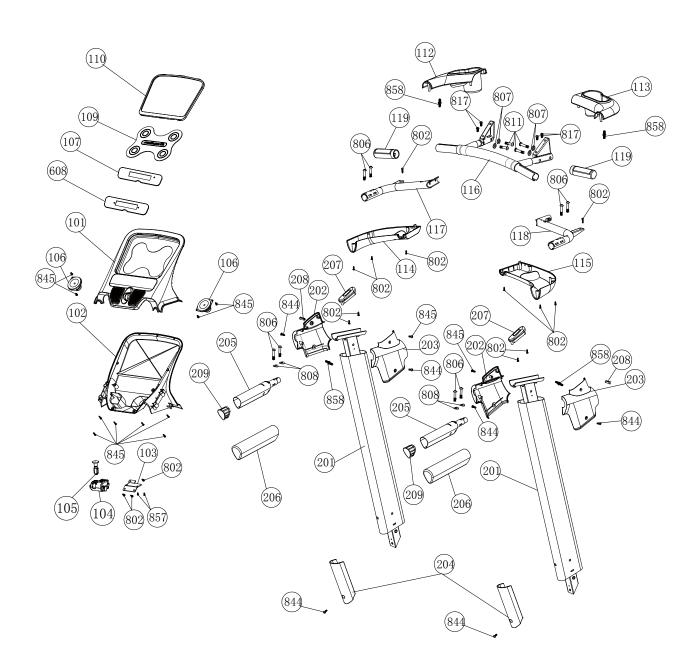
| Part No. | Part name | Quantity |
|----------|--------------------------------------|----------|
| 404 | Motor hood decorate strip-Left | 1 |
| 405 | Motor hood decorate strip-Right | 1 |
| 406 | Motor hood vent cover | 1 |
| 408 | Motor | 1 |
| 409 | Motor holder | 1 |
| 410 | Driving belt | 1 |
| 412 | Elevation motor gear sleeve assembly | 1 |
| 416 | Power switch board | 1 |
| 501 | Running belt | 1 |
| 502 | Running deck | 1 |
| 503 | Side rail | 2 |
| 504 | Side rail decorate strip | 2 |
| 505 | Side rail rear cap-Left | 1 |
| 506 | Side rail rear cap-Right | 1 |
| 507 | Side rail guider | 10 |
| 601 | Elevation motor | |
| 602 | Motor control board | 1 |
| 603 | Transformer | 1 |
| 618 | 8 PIN cable-Upper 750mm | 1 |
| 617 | 8 PIN cable-Upper 2250mm | 1 |
| 612 | Blue/Grey 2 cables-Upper 750mm | 1 |
| 613 | Blue/Grey 2 cables-Lower 2250mm | 1 |
| 610 | Single wire-red-150mm | 2 |
| 611 | Single wire-white-150mm | 1 |
| 607 | Grounding wire-450mm | 1 |

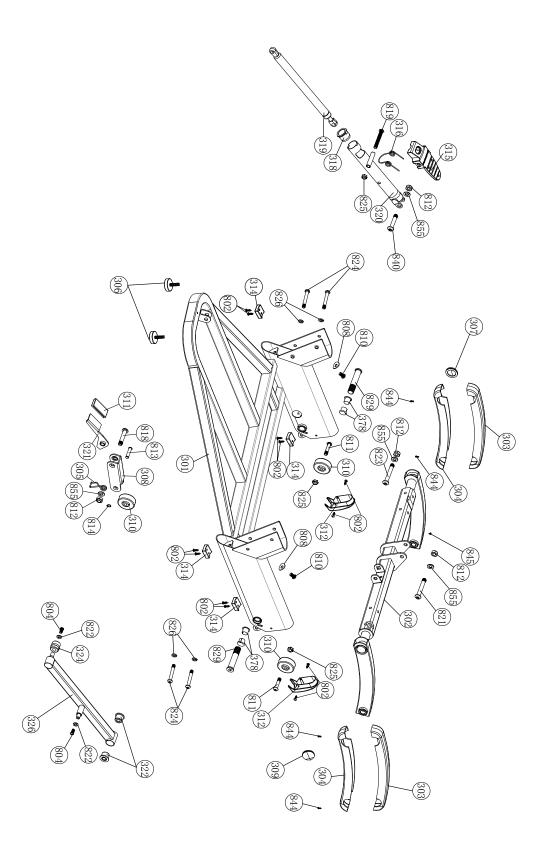
| Part No. | Part name | Quantity |
|----------|--|----------|
| 604 | Handle pluse sensor wire-600mm | 2 |
| 616 | 6PIN cable-220mm | 1 |
| 609 | Motion control sensor wire-red 600mm | 1 |
| 608 | Motion control sensor wire-black 600mm | 1 |
| 614 | Grounding wire-300mm | 1 |
| 604 | Elevation control board | 1 |
| 605 | Electric Protector | 1 |
| 606 | Electric Outlet | 1 |
| 607 | Power Switch | 1 |
| 608 | Computer assembly | 1 |
| 701 | Main frame | 1 |
| 703 | Rear Roller Tube+Shaft | 1 |
| 704 | Front Roller Tube+Shaft | 1 |
| 705 | Rear Caster | 2 |
| 706 | Nylon25.6X25X41.6XR17 | 4 |
| 707 | Ruber cushion with shaft | 2 |
| 708 | Elevation support tube fix holder | 2 |
| 709 | Main frame cross bar | 2 |
| 710 | EVA foam 15XL450XT3.0 | 2 |
| 711 | EVA foam 25XL300XT3.0 | 7 |
| 802 | M4X15 Screw | 44 |
| 804 | M6X17 Screw/Washer | 2 |
| 806 | Button head inner hexagon M8X42 | 8 |
| 807 | Spring washer § 8X 14 X2 | 10 |
| 808 | Curve washer § 8.5X20.5X2 | 6 |

| Part No. | Part name | Quantity |
|----------|--|----------|
| 809 | Round head cross- screw M3X8 | 2 |
| 810 | Button head inner hexagon M8X18 | 4 |
| 811 | Button head inner hexagon M8X36 | 6 |
| 812 | Locknut M10 | 6 |
| 813 | ∮ 8X36 Bolt | 1 |
| 814 | M8 C-clip | 1 |
| 815 | M5X14 screw/washer | 2 |
| 817 | Round head cross- screw M5X14 | 8 |
| 818 | Inner hexagon M10X52 | 1 |
| 819 | Button head inner hexagon M8X65 | 1 |
| 821 | Button head inner hexagon screw M10X67 | 1 |
| 822 | Washer ∮ 6X13X1.5 | 2 |
| 823 | Button head inner hexagon M10X58 | 1 |
| 824 | Button head inner hexagon M8X52 | 4 |
| 825 | Locknut M8 | 5 |
| 826 | Washer § 8X17X1.5 | 10 |
| 827 | Inner hexagon M8X20X20 | 4 |
| 828 | M10X116 Bolt | 1 |
| 829 | Flat head inner hexagon M14X80X24.5 | 2 |
| 830 | M8X48X10 Bolt | 1 |
| 831 | OD8XM8X85X20 Bolt | 1 |
| 832 | Washer § 8X26X3 | 2 |
| 833 | 8X26X11 rubber bushing | 1 |
| 834 | Inner hexagon M8X12X12 | 2 |
| 835 | M4X19 screw | 16 |

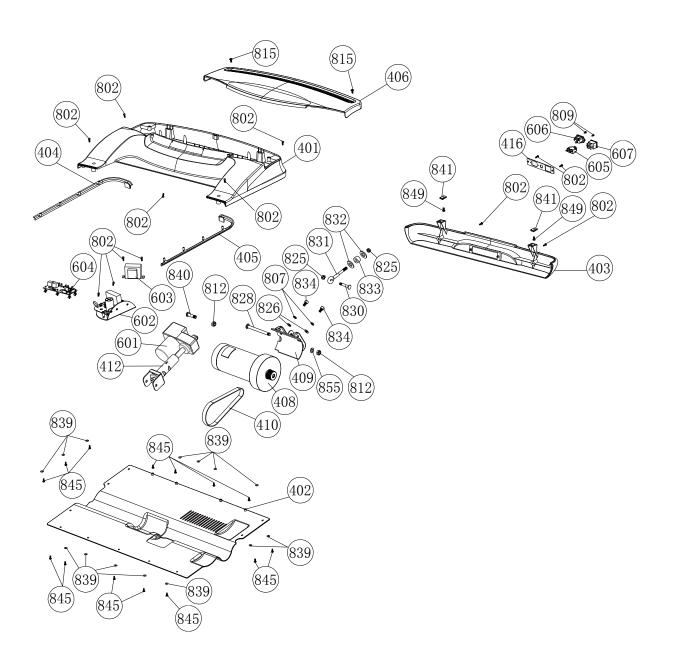
| Part No. | Part name | Quantity |
|----------|-------------------------------------|----------|
| 836 | Cross-screw M8X25 | 4 |
| 837 | Inner hexagon M6X70 | 1 |
| 838 | Inner hexagon M6X55 | 2 |
| 839 | Washer ∮ 6X13X1.5 | 17 |
| 840 | Button head inner hexagon M10X38X10 | 4 |
| 841 | Shrapnel 21X13X0.7 | 2 |
| 844 | M4X15 screw | 10 |
| 845 | M4X12 screw | 27 |
| 848 | Cross-screw M8X30 | 10 |
| 849 | 4.2X16 Screw | 2 |
| 852 | Outer hexagon screw M5X15 | 2 |
| 855 | Washer § 10X20X1.5 | 7 |
| 856 | Thin Nut M5 | 4 |
| 857 | Cross-screw M4X12 | 2 |
| 858 | Plastic insert | 4 |
| 901 | Hardware Kit | 1 |

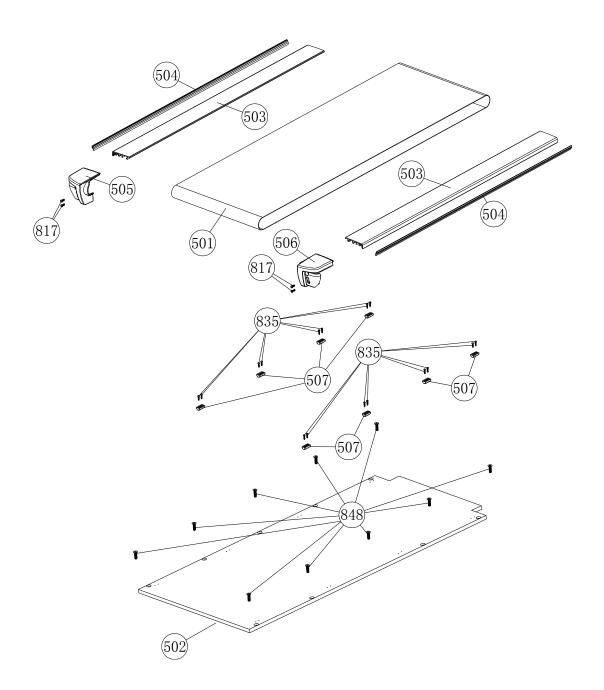
Parts Explosive Drawing

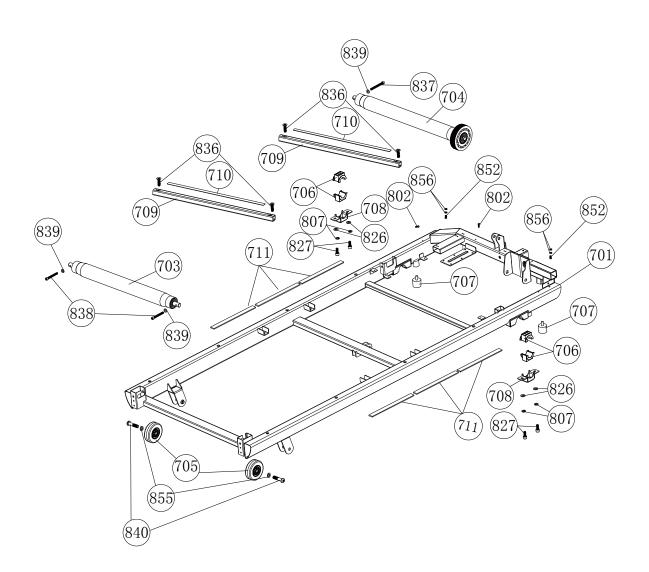




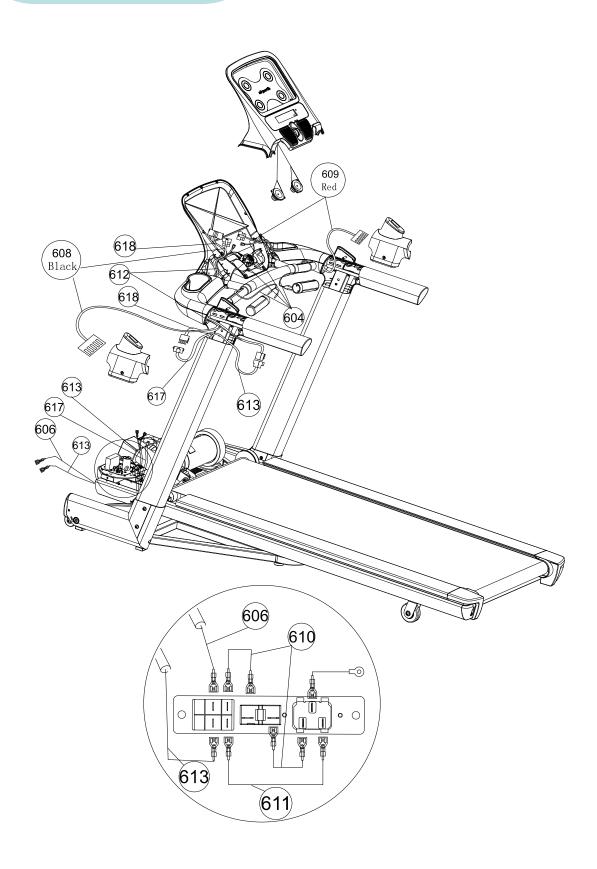
Page 5

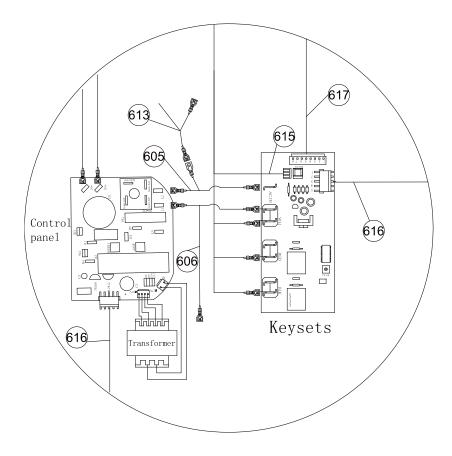


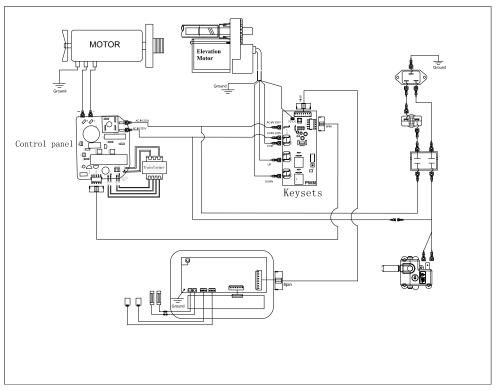




Wire Diagram



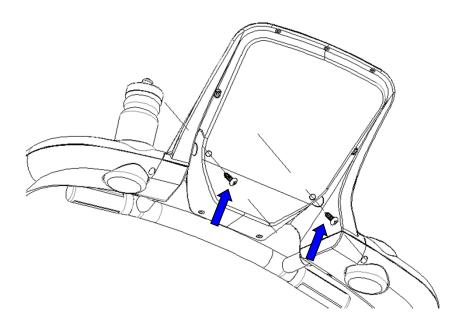




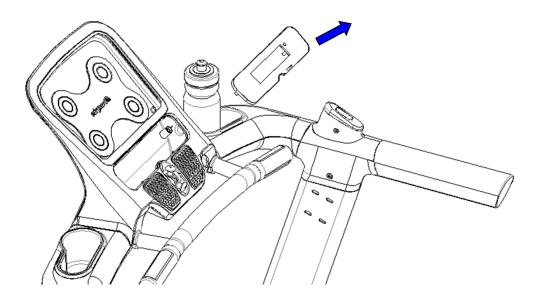
Tools require for service procedure

- 1. Digitize display multi meter
- 2. 17mm wrench 2pcs
- 3. 13mm wrench
- 4. 10mm wrench
- 5. Phillips screwdriver
- 6. 5mm Allen wrench
- 7. 6mm Hex. L-Shape wrench
- 8. 8mm Hex. L-Shape wrench
- 9. 5mm Hex. wrench with T hand bar
- 10. 6mm Hex. wrench with T hand bar
- 11. Long nose plier
- 12. Shorter Phillips screwdriver

Remove Computer for RUN4.1

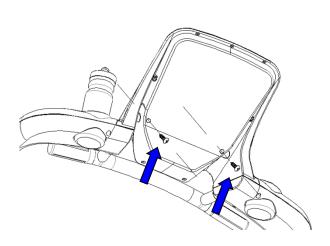


Step 1: Use Phillip screwdriver to open fix console PC board insert 2 screws.

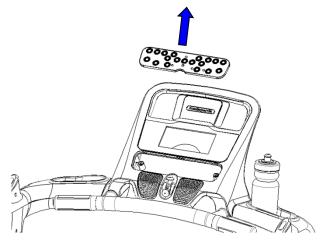


Step 2: Disconnect all connector on computer then remove the console PC board insert.

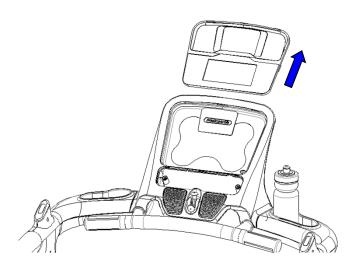
Remove Computer for RUN4.2



Step 1: Use Phillip screwdriver to open fix console buttons panel 2 screws.

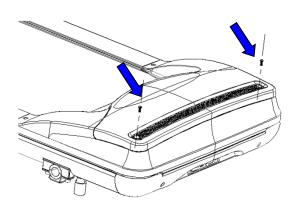


Step 2: Disconnect all connectors then remove buttons panel 2 screws.

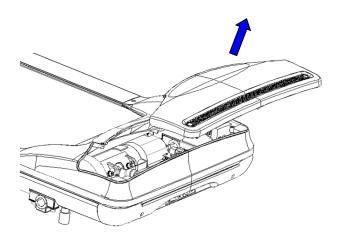


Step 2: Disconnect all connector on computer then remove the console display PC board insert.

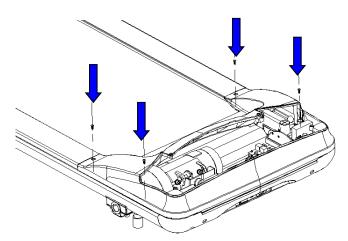
Remove Motor Hood



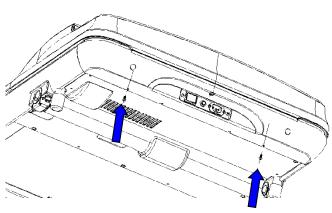
Step 1: Use Phillip screwdriver to open top motor hood vent cover 4 screws.



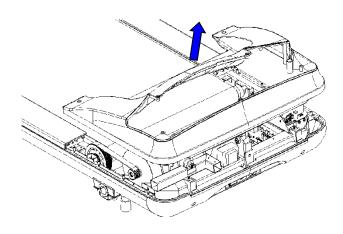
Step 2: Remove top motor hood vent cover.



Step 3: Use Phillip screwdriver to open near both side rail 2 screws and both side 2 screws on the motor hood cover.



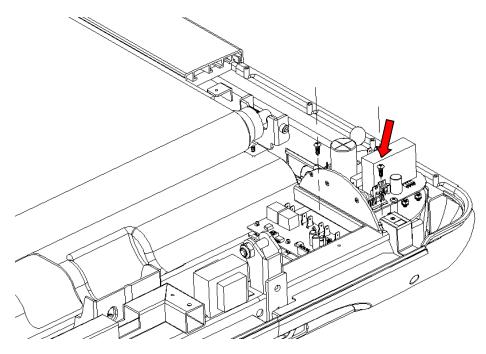
Step 4: Use Phillip screwdriver to open 2 screws on the front motor botton cover.



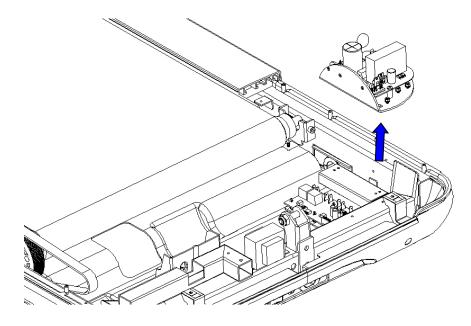
Step 5: Remove motor hood cover.

Remove Main Control Board

Step 1: Follow *Remove Motor Hood* instruction to remove the motor hood.



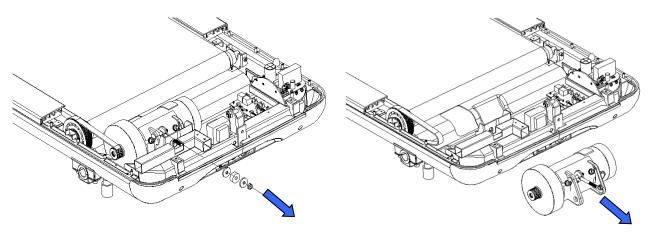
Step 2: Use Phillip screwdriver to open fix low control board 2 screws then disconnect all connector on low control board.



Step 3: Remove lower control board from frame.

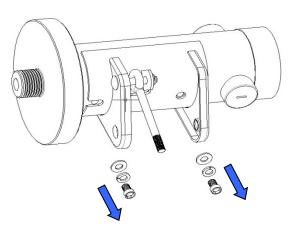
Remove Drive Motor

Step 1: Follow *Remove Motor Hood* instruction to remove the motor hood.



Step 2: Use 17mm wrench to open drive motor bracket tension nut, then remove washers and tension spring.

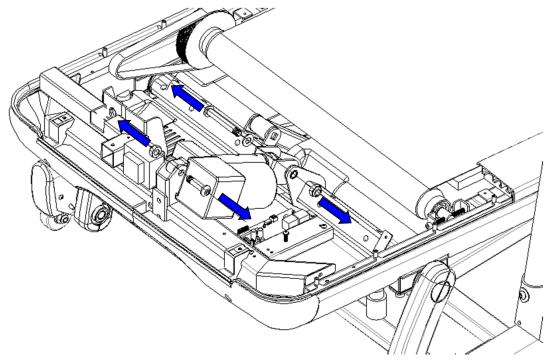
Step 3: Remove the Drive Motor and motor bracket set.



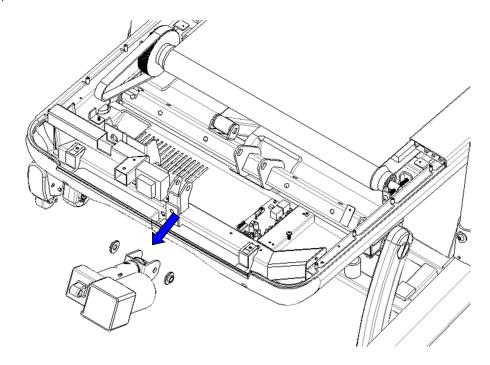
Step 4: Use 5mm Hex. L-Shape wrench to open Drive Motor bracket.

Remove Elevation Motor

Step 1: Follow *Remove Motor Hood* instruction to remove the motor hood.



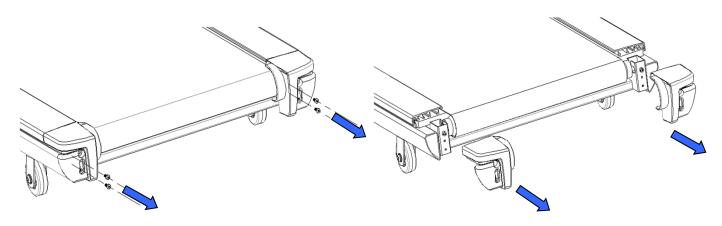
Step 2: Use 17mm wrench and 6mm Allen wrench to open fix elevation bolt and nut on the frame then open bolt and nut on the elevation frame.



Step 3: Remove elevation motor set.

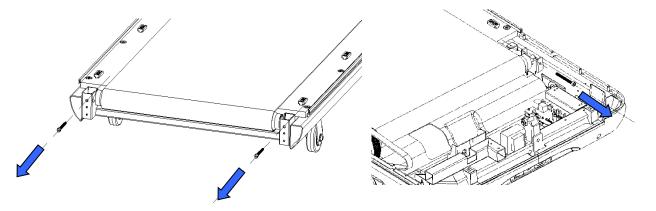
Remove Front and Rear roller

Step 1: Follow *Remove Motor Hood* instruction to remove the motor hood.



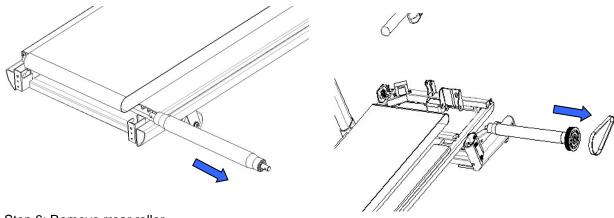
Step 2: Use Phillip screwdriver to open both side rail End covers then remove the cover.

Step 3: Remove both end covers.



Step 3: Use 5mm Allen wrench to open fix rear roller 2 bolts.

Step 5: Use 5mm Allen wrench to open fix front roller 1 bolt.



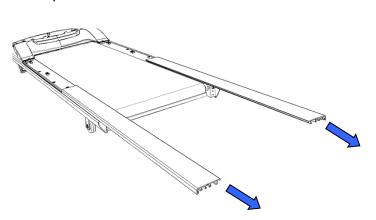
Step 6: Remove rrear roller.

Step 4: Remove front roller.

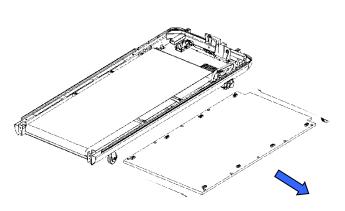
Remove Running Desk and Running Belt

Step 1: Follow *Remove Motor Hood* instruction to remove the motor hood.

Step 2: Follow Remove Front and Rear roller instruction to remove front and rear roller.

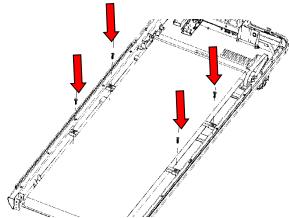


Step 3: Remove both side rail to frame end.

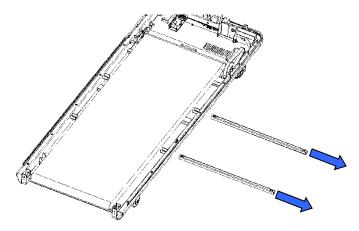


Step 5: Remove the running desk.





Step 6: Use Phillip screwdriver to open running desk support tube 4 bolts.



Step 5: Remove the running desk support tube the remove the running belt.

Lubricate Running belt and running desk

ATTENTION:

To lubricate between running belt and running desk in regular time and after running belt, running desk replacement, otherwise will cause driver DC motor and main control board burn out.

Regular maintain lubricate:

Every time maintain lubricate must additional silicon oil at least 20-25ml.

While treadmill used accumulate time 60-70 hour or every 3-4 months must do lubricate between running belt and running desk.



Step 1: To lift up running one edge side then spray in 10ml silicon oil.



Step 2: To lift up running another edge side then spray in 10ml silicon oil again.

Lubricate after running belt replacement :

After replace running belt must additional silicon oil at least 40-50ml.

Before install new running belt, put new belt on the ground then prop open belt, pour down 20-25ml silicon oil by "S" track, then do another inside belt at same way.



Step 1: pour down 20-25ml silicon oil by "S" track.



Step 2: Do another side at same way.

Lubricate after running desk replacement :

After replace running belt must additional silicon oil at least 20-25ml.

Before install new running desk, put new desk on the ground then pour down 20-25ml silicon oil by "S" track, then use a hairbrush to even wipe silicon oil on desk running face.



Step 1: pour down 20-25ml silicon oil by "S" track.



Step 2: Use hairbrush to even wipe silicon oil on desk running face.



Step 3: The desk after wipe silicon oil.

Install and adjust main control board

When install a new main control board must adjust **SPEED** and **AMP** both VR at main control board before calibration SPEED from computer service set operation.

Confirm the new control board voltage 230VAC correct. (see Fig.1).

Before install a new main control board on unit frame, first adjust **SPEED** and **AMP** both VR (see **Fig.2**), all turn VR at middle. After complete install a new main control board include plugged all connector at main control board then switch power on treadmill and insert safety Key, and press START button set console speed at 0.8kph(0.5mph).

Use a VR adjuster turn **SPEED** VR to counter clockwise and use a RPM or SPEED meter to measure actual speed on running belt moving at same time, still running belt speed at 0.8kph(0.5mph).

After finished adjust **SPEED** VR then adjust **AMP** VR, it's for adjust torque while unit at 0.8kph(0.5mph) speed. When running belt moving at 0.8kph(0.5mph), first step two hands hold and firm at front handle bar or both side rail handle bar then move feet on running belt and a little bit to resist Running belt, if running belt stop then adjust **AMP** VR to counter clockwise a little bit, after adjust **AMP** VR then use foot test again, repeat this test action couple times, still running belt not stop from foot little force.

Attention:

If adjust *AMP* VR too much higher, when user workout at treadmill running belt will suddenly speed up at short time during every pace. *Do not adjust AMP VR too much higher because it's will to bring DC driver short life.*





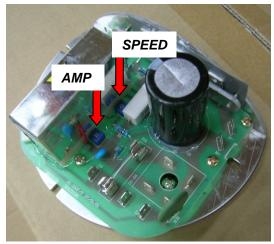


Fig.2

Install and adjust elevation motor

Before install a new elevation motor must confirm voltage and model correct from elevation motor label. (see *Fig.1*).

When install a new elevation motor, first only fix new elevation motor rear body on unit main frame and connection all elevation motor wires on incline relay board. (see *Fig.2*). Next step switch treadmill power on, insert safety key then press START button, elevation motor will Automatic turn to level "0" position.

Take elevation nut tube to turn in elevation spiral bar, still elevation nut tube top edge near Elevation motor body position.(see *Fig.2*)

After complete elevation motor all install then follow service set instruction to calibrate incline.



Fig.1



Fig.2

Error Code

Computer show "Err 2" while turn power on

Switch power on and press **INCLINE Up + INCLINE DOWN + STOP/ENTER** button and hold them, then pull on emergency stop switch, computer show "1" blinking, use **INCLINE UP** and **INCLINE DOWN** to select computer show "2" blinking, then press **START** button to enter the Incline Calibration Procedure.

Incline Level display shows "0". Press Incline up and Down button to adjust the deck to horizontal position then press STOP/ENTER button to confirm the 0 level.

After set the 0 level, Incline Level display show "12" and the treadmill will automatically incline up. Waiting for treadmill incline stop, press Incline up and Down button to adjust incline level 12 correct position, then press STOP/ENTER twice to confirm the level 12 position and return computer power on status.

Computer show " " oil can or "Ser" for reset

Computer can display service maintain used mileage for service technical engineer check, this maintain mileage for cycle every **300km(186ml)** to remind unit owner to maintain treadmill on regular time. when showing maintain mileage can press SPEED DOWN button to reset.

Switch power on and press SPEED UP and DOWN button and hold them then insert safety key. Press INCLINE UP and DOWN button to select computer display show "3", blinking then press START button, computer will display maintain mileage, press SPEED DOWN button can reset maintain mileage, then press ENTER button twice return to power on status.

Engineer mode Setting

Conversion console display in Metric(km) or English(ml)

Switch the power on, press and hold **START** button and hold them, then pull up the safety key, console will display "KM" or "ML", use **START** button to select between "KM" and "ML", then press **STOP/ENTER** to confirm and return power on status.

Enter the service Engineer Mode

Switch the power on, press and hold **INCLINE UP** and **DONW** and **STOP/ENTER** 3 buttons and hold them, then pull up the safety key to enter the ENGINEER MODE. Time/Distance display shows "1" and blinking.

Set and display the manufacture date and software version

Press START button, Time/Distance display shows the manufacture YEAR, Heart Rate display shows manufacture MONTH, Calories display shows manufacture DATE. Speed display shows software version. The service engineer can adjust the manufacture date by pressing Incline Up and Down button follow the blinking display then press **STOP/ENTER** button after each adjustment to record the service date if necessary. After all the adjustment done, press **STOP/ENTER** button again to exit the Engineer Mode.

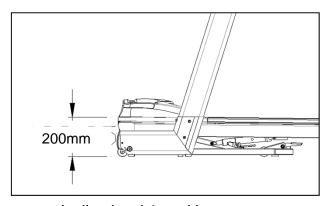
Incline Calibration

Enter Engineer mode.

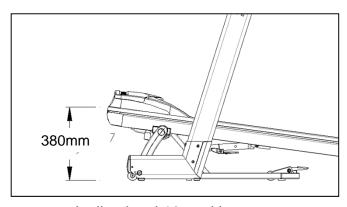
Press **INCLINE UP** and **DOWN** button to select computer display shows "2" then press **START** button to enter the Incline Calibration Procedure.

Incline Level display shows "0". Press **INCLINE UP** and **DOWN** button to bring the deck to horizontal position then press **STOP/ENTER** button to set the L0 level.

After set the L0 level, Incline Level display shows "12" and the treadmill will automatically incline up. Waiting for treadmill incline stop, press **INCLINE UP** and **DOWN** button to adjust incline L12 correct position, then press **STOP/ENTER** twice to set the L12 level and exit the engineer mode.



Incline level 1 position



Incline level 12 position

Speed Calibration

Enter Engineer mode.

Press **INCLINE UP** and **DOWN** button to select computer display shows "**3**" then press **START** button to enter the Speed Calibration Procedure.

Speed display shows "0.5"mph or "0.8"kph. Press **SPEED UP** and **DOWN** button to adjust the actual speed and measure the belt speed by speed meter then press **STOP/ENTER** button to set the lowest speed.

After set the lowest speed, Speed display shows "10"mph or "16"kph then treadmill speed will start increase. Wait till treadmill stop increase the speed, measure the belt speed by speed meter and press **SPEED UP** and **DOWN** to adjust the actual speed then press **STOP/ENTER** button twice to exit the Engineer mode.

SLEEP / DISPLAY Mode

When the power is ON the computer will automatically enter SLEEP MODE if it is left idle for 3 minutes without receiving any input. Press any button to return to POWER ON status when the computer is in the SLEEP MODE.

To cancel the SLEEP MODE feature using the DISPLAY MODE and always keep the console display on, pull out the safety key, press and hold the **SPEED UP** and **DOWN** buttons, insert the safety key to power on the treadmill. After one short beep sound the PULSE/INCLINE level display window show "1" and blinking. Press **START** button the TIME LED window will show "ON" (SLEEP MODE feature on) or "OFF" (SLEEP MODE feature off). Press the **INCLINE UP** and **DOWN** buttons to switch between "ON" and "OFF" then press **STOP/ENTER** to save the setting and return to POWER ON mode.

Set console buzzer sound on/off

Power on and pull out the safety key, press and hold the **SPEED UP** and **DOWN** buttons, pull up the safety key to power on the treadmill. After one short beep sound the PULSE/INCLINE level display window show "1" and blinking. Press the **INCLINE UP** and **DOWN** buttons to select show "2" then press **START** button, computer will show "ON" or "OFF", press **INCLINE UP** and **DOWN** to select between on/off then press **STOP/ENTER** button twice return power status.

Check and reset maintain mileage

Computer can display service maintain used mileage for service technical engineer check, this maintain mileage for cycle every 300km(186ml) to remind unit owner to maintain treadmill on regular time. when showing maintain mileage can press **SPEED DOWN** button to reset.

Power switch on and press **SPEED UP** and **DOWN** button and hold them then pull up safety key. Press INCLINE UP and DOWN button to select PULSE/INCLINE level display window show "3", then press **START** button, computer will display maintain mileage, press **SPEED DOWN** button can reset maintain mileage, press **STOP/ENTER** button twice return to power on status.

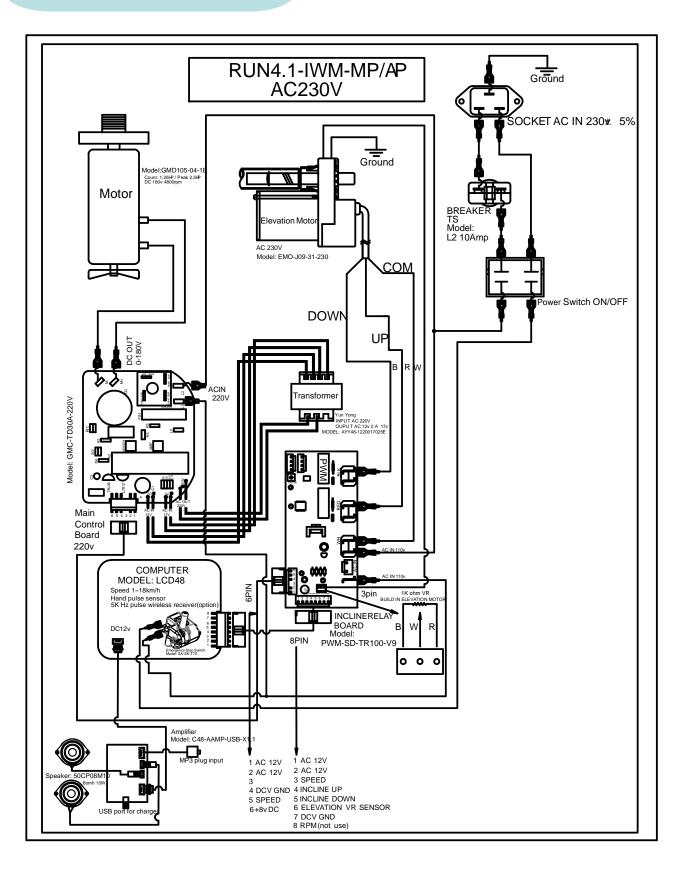
Display accumulate used mileage

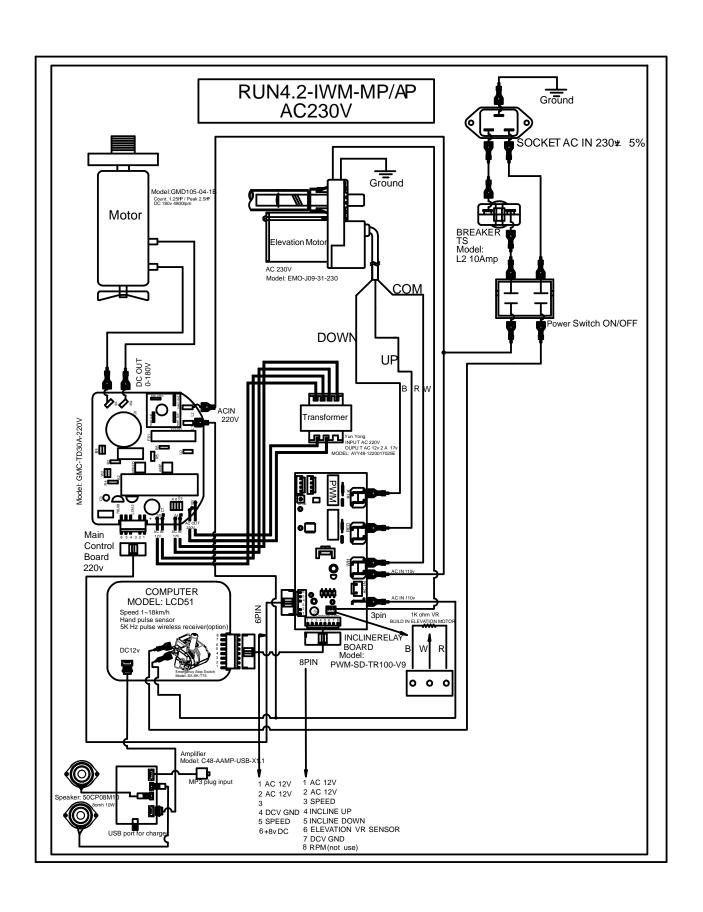
Power switch on and press **SPEED UP** and **DOWN** button and hold them then pull up safety key. Press **INCLINE UP** and **DOWN** button to select PULSE/INCLINE level display window show "4", then press **START** button, computer will display total used mileage, press **STO/ENTER** button twice return to power on status.

Display accumulate used hours

Power switch on and press **SPEED UP** and **DOWN** button and hold them then insert safety key. Press **INCLINE UP** and **DOWN** button to select PULSE/INCLINE level display window show "5", then press **START** button, computer will display total used hours, press **STOP/ENTER** button twice return to power on status.

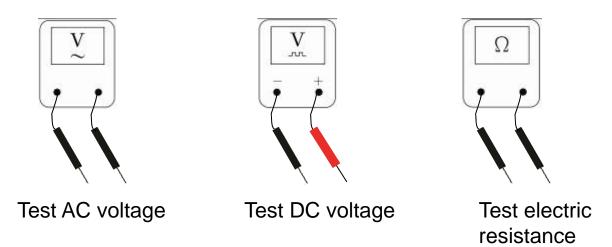
Treadmill circuit Diagram





Trouble Shooting

Electro-meter icon test instruction:



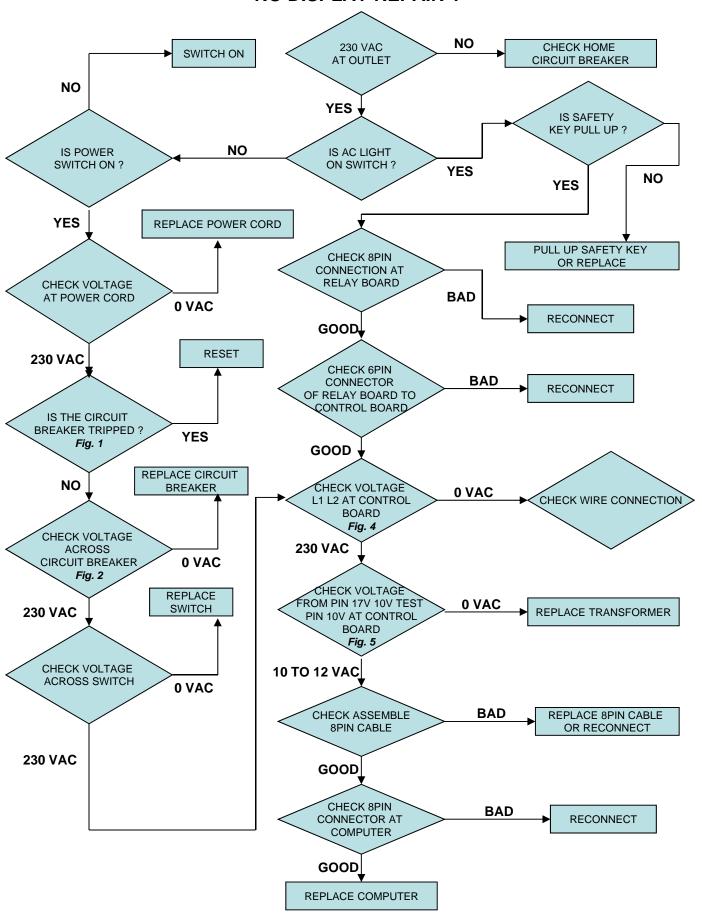


Press START button at 0.8kph(0.5mph) speed.



Press START button then continuous adjust speed to top speed.

NO DISPLAY REPAIR-1



NO DISPLAY REPAIR-2

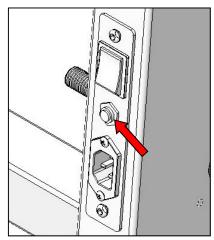


Fig. 1: Is circuit tripped? press button to reset.

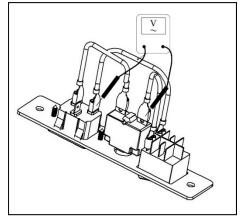


Fig. 2: Check voltage across circuit breaker.

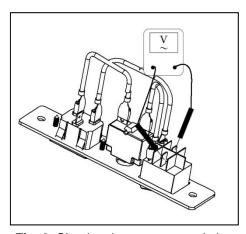


Fig. 3: Check voltage across switch.

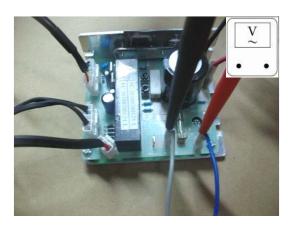


Fig. 4: Check voltage L1, L2 at main control board.

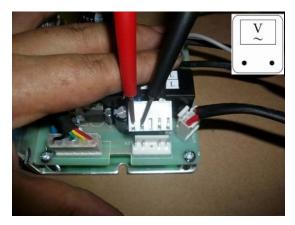
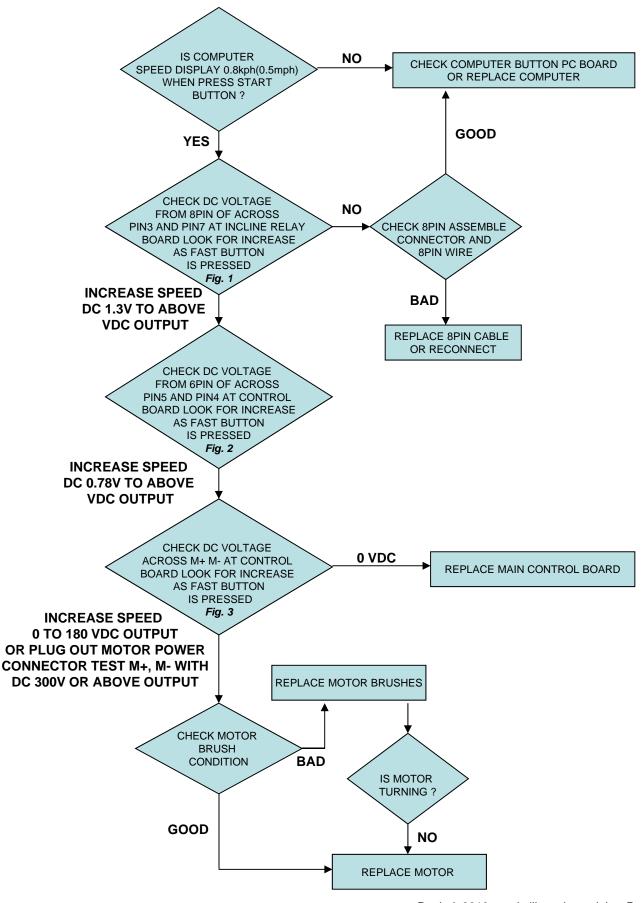


Fig. 5: Check voltage from pin 17v 10v, test pin 10v at main control board.

NO BELT MOVEMENT REPAIR-1



NO BELT MOVEMENT REPAIR-2

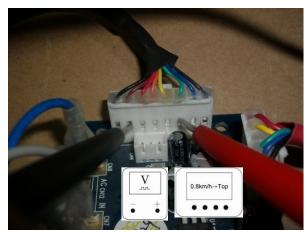


Fig. 1: Check DC voltage from 8pin of across pin3 and pin7 at incline relay board check for increase as fast button is pressed.

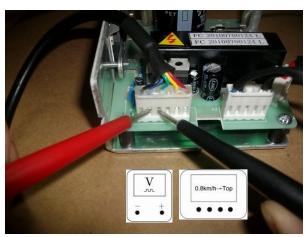


Fig. 2: Check DC voltage from 6pin of across pin4 and pin5 at main control board check for increase voltage as press SPEED UP button is pressed.

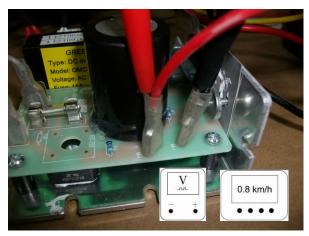
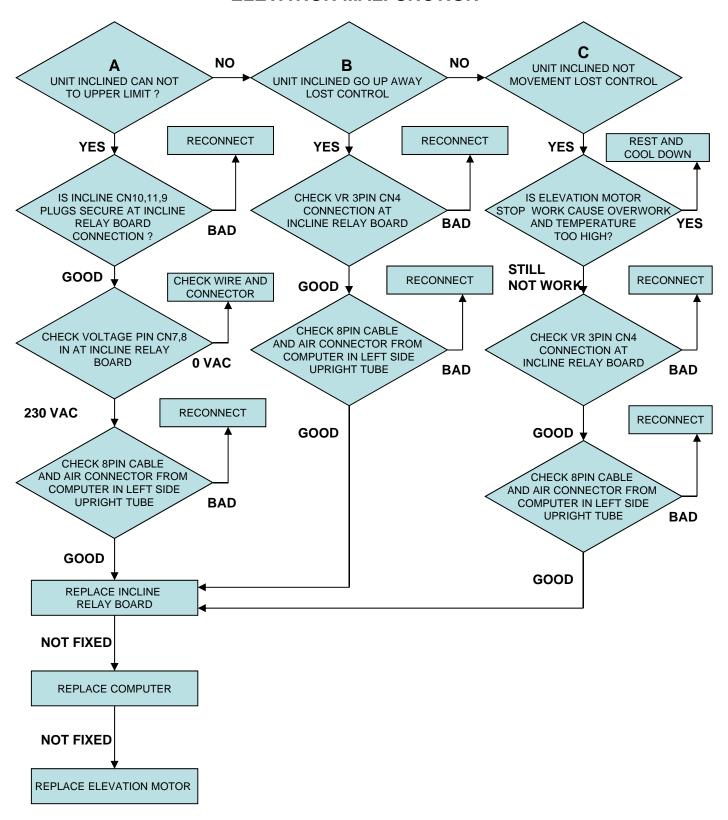


Fig. 3: Check DC voltage across M+, M- at main control board check for increase as fast button is pressed.

ELEVATION MALFUNCTION



HEART RATE(HR) NOT FUNCTIONING/ ERRATIC READING

